## Ordinary Differential Equations

Initial Value Problem (IVP)
$y^{\prime \prime}=f\left(x, y, y^{\prime}\right) \quad x>0 \quad$ with $\quad y(0)=y_{0}, y^{\prime}(0)=y_{0}^{\prime}$

Boundary Value Problem (BVP)

$$
y^{\prime \prime}=f\left(x, y, y^{\prime}\right) \quad a<x<b \quad \text { with } \quad y(a)=y_{a}, y(b)=y_{b}
$$

Initial Value Problem, $1^{\text {st }}$ order
$y^{\prime}=f(t, y) \quad t>0 \quad$ with $\quad y(0)=y_{0}$
forward difference approximation of $y^{\prime}=\frac{y(t+h)-y(t)}{h}$
$\Rightarrow y(t+h)=y(t)+h f(t, y)$

Seek for solution in $t_{0} \leq t \leq t_{n}$ with

$$
\begin{aligned}
& t_{i}=t_{0}+i h \quad i=0,1, \ldots, M \\
& t_{i+1}-t_{i}=h \quad \text { and } \quad h=\frac{t_{n}-t_{0}}{M} \\
& \Rightarrow y_{i+1}=y_{i}+h f\left(t_{i}, y_{i}\right) \quad \text { Euler approximation }
\end{aligned}
$$

## Example

$y^{\prime}=\frac{t-y}{2} \quad y(0)=1$
Find $y(t)$ for $0 \leq t \leq 3$ with $h=1$
$y_{i+1}=y_{i}+h f\left(t_{i}, y_{i}\right)=y_{i}+\frac{t_{i}-y_{i}}{2}=\frac{t_{i}+y_{i}}{2}$

| i | $\mathrm{t}_{\mathrm{i}}$ | $\mathrm{y}_{\mathrm{i}}$ |
| :--- | :--- | :--- |
| 0 | 0 | 1 |
| 1 | 1 | $(0+1) / 2=0.5$ |
| 2 | 2 | $(1+0.5) / 2=0.75$ |
| 3 | 3 | $(0.75+2) / 2=1.375$ |

As $h$ gets smaller we approach the exact solution.


$$
\begin{aligned}
& y^{\prime}=\frac{t-y}{2} \quad y(0)=1 \\
& \text { Find } \quad y(t) \quad \text { for } \quad \mathbf{0} \leq t \leq 3 \quad \text { with } \quad h=1 \\
& y_{i+1}=y_{i}+h f\left(t_{i}, y_{i}\right)=y_{i}+\frac{t_{i}-y_{i}}{2}
\end{aligned}
$$

Figure 9.5 Euler's approximations


## Geometric Description

If you start at the point $\left(t_{0}, y_{0}\right)$ and compute the value of the slope $m_{0}=f\left(t_{0}, y_{0}\right)$ and move horizontally the amount $h$ and vertically $h f\left(t_{0}, y_{0}\right)$, then you are moving along the tangent line to $y(t)$ and will end up at the point $\left(t_{1}, y_{1}\right)$ (see Figure 9.5). Notice that $\left(t_{1}, y_{1}\right)$ is not on the desired solution curve! But this is the approximation that we are generating. Hence we must use $\left(t_{1}, y_{1}\right)$ as though it were correct and proceed by computing the slope $m_{1}=f\left(t_{1}, y_{1}\right)$ and using it to obtain the next vertical displacement $h f\left(t_{1}, y_{1}\right)$ to locate ( $t_{2}, y_{2}$ ), and so on.

Example 9.4. Use Euler's method to solve the I.V.P.

$$
y^{\prime}=\frac{t-y}{2} \quad \text { on }[0,3] \text { with } y(0)=1 .
$$

Compare solutions for $h=1, \frac{1}{2}, \frac{1}{4}$, and $\frac{1}{8}$.

Table 9.2 Comparison of Euler Solutions with Different Step Sizes for $y^{\prime}=(t-y) / 2$ over $[0,3]$ with $y(0)=1$

| $t_{k}$ | $y_{k}$ |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | $h=1$ | $h=\frac{1}{2}$ | $h=\frac{1}{4}$ | $h=\frac{1}{8}$ | $y\left(t_{k}\right)$ Exact |
| 0 | 1.0 | 1.0 | 1.0 | 1.0 |  |
| 0.125 |  |  |  | 0.9375 | 0.943239 |
| 0.25 |  |  | 0.875 | 0.886719 | 0.897491 |
| 0.375 |  |  |  | 0.846924 | 0.862087 |
| 0.50 |  | 0.75 | 0.796875 | 0.817429 | 0.836402 |
| 0.75 |  |  | 0.759766 | 0.786802 | 0.811868 |
| 1.00 | 0.5 | 0.6875 | 0.758545 | 0.790158 | 0.819592 |
| 1.50 |  | 0.765625 | 0.846386 | 0.882855 | 0.917100 |
| 2.00 | 0.75 | 0.949219 | 1.030827 | 1.068222 | 1.103638 |
| 2.50 |  | 1.211914 | 1.289227 | 1.325176 | 1.359514 |
| 3.00 | 1.375 | 1.533936 | 1.604252 | 1.637429 | 1.669390 |



Figure 9.6 Comparison of Euler solutions with different step sizes for $y^{\prime}=(t-y) / 2$ over [0,3] with the initial condition $y(0)=1$.

## Error in Euler

$$
\begin{gathered}
y(t)=y\left(t_{0}\right)+y^{\prime}\left(t_{0}\right)\left(t-t_{0}\right)+\frac{y^{\prime \prime}\left(c_{1}\right)\left(t-t_{0}\right)^{2}}{2} . \\
y^{\prime}\left(t_{0}\right)=f\left(t_{0}, y\left(t_{0}\right)\right) \text { and } h=t_{1}-t_{0} \\
y\left(t_{1}\right)=y\left(t_{0}\right)+h f\left(t_{0}, y\left(t_{0}\right)\right)+y^{\prime \prime}\left(c_{1}\right) \frac{h^{2}}{2} . \\
y_{1}=y_{0}+h f\left(t_{0}, y_{0}\right), \quad \text { Euler approximation } \\
y^{\prime \prime}\left(c_{1}\right) \frac{h^{2}}{2} \quad \rightarrow \quad \text { Local discretization error } \\
\sum_{k=1}^{M} y^{(2)}\left(c_{k} \frac{h^{2}}{2} \approx M y^{(2)}(c) \frac{h^{2}}{2}=\frac{h M}{2} y^{(2)}(c) h=\frac{(b-a) y^{(2)}(c)}{2} h=\boldsymbol{O}\left(h^{1}\right)\right. \\
\rightarrow \text { Global discretization error }
\end{gathered}
$$

Final global error: $\quad E(y(b), h)=\left|y(b)-y_{M}\right|=O(h)$.
Example 9.5. Compare the F.G.E. when Euler's method is used to solve the I.V.P.

$$
y^{\prime}=\frac{t-y}{2} \quad \text { over }[0,3] \text { with } y(0)=1,
$$

using step sizes $1, \frac{1}{2}, \ldots, \frac{1}{64}$.
Table 9.3 Relation between Step Size and F.G.E. for Euler Solutions to
$y^{\prime}=(t-y) / 2$ over [0,3] with $y(0)=1$

| Step <br> size, $h$ | Number of <br> steps, $M$ | Approximation <br> to $y(3), y_{M}$ | F.G.E. <br> Error at $t=3$, <br> $y(3)-y_{M}$ | $\boldsymbol{O}(h) \approx C h$ <br> where <br> $C=0.256$ |
| :---: | :---: | :---: | :---: | :--- |
| 1 | 3 | 1.375 | 0.294390 | 0.256 |
| $\frac{1}{2}$ | 6 | 1.533936 | 0.135454 | 0.128 |
| $\frac{1}{4}$ | 12 | 1.604252 | 0.065138 | 0.064 |
| $\frac{1}{8}$ | 24 | 1.637429 | 0.031961 | 0.032 |
| $\frac{1}{16}$ | 48 | 1.653557 | 0.015833 | 0.016 |
| $\frac{1}{32}$ | 96 | 1.661510 | 0.007880 | 0.008 |
| $\frac{1}{64}$ | 192 | 1.665459 | 0.003931 | 0.004 |

How to improve accuracy of Euler's Method?
Consider Taylor series

$$
y(x+h)=y(x)+h y^{\prime}+\frac{h^{2}}{2} y^{\prime \prime}+\frac{h^{3}}{3!} y^{\prime \prime \prime}(\eta)+\ldots
$$

and compute the derivatives as

$$
\begin{aligned}
& y^{\prime}(t)=f \\
& y^{\prime \prime}(t)=f_{t}+f_{y} y^{\prime}=f_{t}+f_{y} f \\
& \ldots \ldots \\
& y(x+h)=y(x)+h f+\frac{h^{2}}{2}\left(f_{x}+f f_{y}\right)+\frac{h^{3}}{3!} y^{\prime \prime \prime}(\eta)
\end{aligned}
$$

$f(x+h)=f(x)+h f^{\prime}(x)+\frac{h^{2} f^{\prime \prime}(x)}{2}+\frac{h^{3} f^{(3)}(x)}{6}+\frac{h^{4} f^{(4)}(x)}{24}+\cdots$

For Taylor's formula of order $N$
Local discretization error $=O\left(h^{N+1}\right)$
Global discretization error $=O\left(h^{N}\right)$

Example 9.8. Use the Taylor method of order $N=4$ to solve $y^{\prime}=(t-y) / 2$ on $[0,3]$ with $y(0)=1$. Compare solutions for $h=1, \frac{1}{2}, \frac{1}{4}$, and $\frac{1}{8}$.

$$
\begin{aligned}
& y(x+h)=y(x)+h y^{\prime}+\frac{h^{2}}{2} y^{(2)}+\frac{h^{3}}{3!} y^{(3)}+\frac{h^{4}}{4!} y^{(4)} \\
& y^{\prime}(t)=\frac{t-y}{2}, \\
& y^{(2)}(t)=\frac{d}{d t}\left(\frac{t-y}{2}\right)=\frac{1-y^{\prime}}{2}=\frac{1-(t-y) / 2}{2}=\frac{2-t+y}{4}, \\
& y^{(3)}(t)=\frac{d}{d t}\left(\frac{2-t+y}{4}\right)=\frac{0-1+y^{\prime}}{4}=\frac{-1+(t-y) / 2}{4}=\frac{-2+t-y}{8}, \\
& y^{(4)}(t)=\frac{d}{d t}\left(\frac{-2+t-y}{8}\right)=\frac{-0+1-y^{\prime}}{8}=\frac{1-(t-y) / 2}{8}=\frac{2-t+y}{16} .
\end{aligned}
$$

Table 9.6 Comparison of the Taylor Solutions of Order $N=4$ for $y^{\prime}=(t-y) / 2$ over $[0,3]$ with $y(0)=1$

| $t_{k}$ | $y_{k}$ |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | $h=1$ | $h=\frac{1}{2}$ | $h=\frac{1}{4}$ | $h=\frac{1}{8}$ | $y\left(t_{k}\right)$ Exact |
| 0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.125 |  |  |  | 0.9432392 | 0.9432392 |
| 0.25 |  |  | 0.8974915 | 0.8974908 | 0.8974917 |
| 0.375 |  |  |  | 0.8620874 | 0.8620874 |
| 0.50 |  | 0.8364258 | 0.8364037 | 0.8364024 | 0.8364023 |
| 0.75 |  |  | 0.8118696 | 0.8118679 | 0.8118678 |
| 1.00 | 0.8203125 | 0.8196285 | 0.8195940 | 0.8195921 | 0.8195920 |
| 1.50 |  | 0.9171423 | 0.9171021 | 0.9170998 | 0.9170997 |
| 2.00 | 1.1045125 | 1.1036826 | 1.1036408 | 1.1036385 | 1.1036383 |
| 2.50 |  | 1.3595575 | 1.3595168 | 1.3595145 | 1.3595144 |
| 3.00 | 1.6701860 | 1.6694308 | 1.6693928 | 1.6693906 | 1.6693905 |

Final global error: $\quad E(y(3), h)=y(3)-y_{M}=O\left(h^{4}\right) \approx C h^{4}$.

Taylor's method is cumbersome from numerical point of view since higher derivatives need to be calculated.
Alternative way to improve accuracy is to use several function evaluations:

$$
y^{\prime}(t)=f(t, y(t)) \quad \text { over } \quad[a, b] \quad \text { with } \quad y\left(t_{0}\right)=y_{0}
$$

integrate $y^{\prime}(t)$ over $\left[t_{0}, t_{1}\right]$ to get
$\int_{t_{0}}^{t_{1}} f(t, y(t)) d t=\int_{t_{0}}^{t_{1}} y^{\prime}(t) d t=y\left(t_{1}\right)-y\left(t_{0}\right)$,
solved for $y\left(t_{1}\right)$

$$
y\left(t_{1}\right)=y\left(t_{0}\right)+\int_{t_{0}}^{t_{1}} f(t, y(t)) d t
$$

If the trapezoidal rule is used with the step size $h=t_{1}-t_{0}$,

$$
\begin{aligned}
& y\left(t_{1}\right) \approx y\left(t_{0}\right)+\frac{h}{2}\left(f\left(t_{0}, y\left(t_{0}\right)\right)+f\left(t_{1}, y\left(t_{1}\right)\right)\right) . \\
& \text { Euler's solution } y\left(t_{1}\right)=y\left(t_{0}\right)+h f\left(t_{0}, y\left(t_{0}\right)\right) \\
& y_{1}=y\left(t_{0}\right)+\frac{h}{2}\left(f\left(t_{0}, y_{0}\right)+f\left(t_{1}, y_{0}+h f\left(t_{0}, y_{0}\right)\right)\right)
\end{aligned}
$$

[^0]\[

$$
\begin{aligned}
& \text { Modified Euler Method } \\
& \text { (use two slopes sequentially) } \\
& y(t+h)=y(t)+h f\left(t+\frac{h}{2}, y+\frac{h}{2} f(t, y)\right)
\end{aligned}
$$
\]

## Runge-Kutta Method :

accuracy of Taylor $\mathrm{N}=4$, no high derivatives, several function evaluations

$$
y_{k+1}=y_{k}+w_{1} k_{1}+w_{2} k_{2}+w_{3} k_{3}+w_{4} k_{4},
$$

where $k_{1}, k_{2}, k_{3}$, and $k_{4}$ have the form

$$
\begin{aligned}
& k_{1}=h f\left(t_{k}, y_{k}\right), \\
& k_{2}=h f\left(t_{k}+a_{1} h, y_{k}+b_{1} k_{1}\right), \\
& k_{3}=h f\left(t_{k}+a_{2} h, y_{k}+b_{2} k_{1}+b_{3} k_{2}\right), \\
& k_{4}=h f\left(t_{k}+a_{3} h, y_{k}+b_{4} k_{1}+b_{5} k_{2}+b_{6} k_{3}\right) .
\end{aligned}
$$

Find $a_{i}, b_{i}$ by matching the Runge-Kutta method to $\mathrm{N}=4$ Taylor method. This results in 11 equations for 13 unknowns.
2 of $a_{\mathrm{i}}, b_{\mathrm{i}}$ are selected and the rest are solved in terms of the selected ones.
the standard Runge-Kutta method of order $N=4$,

$$
y_{k+1}=y_{k}+\frac{h\left(f_{1}+2 f_{2}+2 f_{3}+f_{4}\right)}{6},
$$

where

$$
\begin{aligned}
& f_{1}=f\left(t_{k}, y_{k}\right), \\
& f_{2}=f\left(t_{k}+\frac{h}{2}, y_{k}+\frac{h}{2} f_{1}\right), \\
& f_{3}=f\left(t_{k}+\frac{h}{2}, y_{k}+\frac{h}{2} f_{2}\right), \\
& f_{4}=f\left(t_{k}+h, y_{k}+h f_{3}\right) .
\end{aligned}
$$

$$
\begin{equation*}
y\left(t_{1}\right)-y\left(t_{0}\right)=\int_{t_{0}}^{t_{1}} f(t, y(t)) d t \tag{8}
\end{equation*}
$$

If Simpson's rule is applied with step size $h / 2$, the approximation to the integral in (8) is
(9) $\quad \int_{t_{0}}^{t_{1}} f(t, y(t)) d t \approx \frac{h}{6}\left(f\left(t_{0}, y\left(t_{0}\right)\right)+4 f\left(t_{1 / 2}, y\left(t_{1 / 2}\right)\right)+f\left(t_{1}, y\left(t_{1}\right)\right)\right)$,
where $t_{1 / 2}$ is the midpoint of the interval. Three function values are needed; hence we make the obvious choice $f\left(t_{0}, y\left(t_{0}\right)\right)=f_{1}$ and $f\left(t_{1}, y\left(t_{1}\right)\right) \approx f_{4}$. For the value in the middle we chose the average of $f_{2}$ and $f_{3}$ :

$$
f\left(t_{1 / 2}, y\left(t_{1 / 2}\right)\right) \approx \frac{f_{2}+f_{3}}{2} .
$$

These values are substituted into (9), which is used in equation (8) to get $y_{1}$ :
(10)

$$
y_{1}=y_{0}+\frac{h}{6}\left(f_{1}+\frac{4\left(f_{2}+f_{3}\right)}{2}+f_{4}\right)
$$


(a) Predicted slopes $m_{j}$ to the solution curve $y=y(t)$

(b) Integral approximation:

$$
y\left(t_{1}\right)-y_{0}=\frac{h}{6}\left(f_{1}+2 f_{2}+2 f_{3}+f_{4}\right)
$$

Figure 9.9 The graphs $y=y(t)$ and $z=f(t, y(t))$ in the discussion of the Runge-Kutta method of order $N=4$.
error in Simpson $\sim O\left(h^{5}\right)$; accumulated error in Runge-Kutta after M steps $\sim O\left(h^{4}\right)$

Example 9.11. Compare the F.G.E. when the RK4 method is used to solve $y^{\prime}=(t-y) / 2$ over $[0,3]$ with $y(0)=1$ using step sizes $1, \frac{1}{2}, \frac{1}{4}$, and $\frac{1}{8}$.

Table 9.8 Comparison of the RK4 Solutions with Different Step Sizes for $y^{\prime}=(t-y) / 2$ over $[0,3]$ with $y(0)=1$

|  | $y_{k}$ |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :--- |
| $t_{k}$ | $h=1$ | $h=\frac{1}{2}$ | $h=\frac{1}{4}$ | $h=\frac{1}{8}$ | $y\left(t_{k}\right)$ Exact |
| 0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 |
| 0.125 |  |  |  | 0.9432392 | 0.9432392 |
| 0.25 |  |  | 0.8974915 | 0.8974908 | 0.8974917 |
| 0.375 |  |  |  | 0.8620874 | 0.8620874 |
| 0.50 |  |  | 0.8364037 | 0.8364024 | 0.8364023 |
| 0.75 |  | 0.8118696 | 0.8118679 | 0.8118678 |  |
| 1.00 | 0.8203125 | 0.8196285 | 0.8195940 | 0.8195921 | 0.8195920 |
| 1.50 |  | 0.9171423 | 0.9171021 | 0.9170998 | 0.9170997 |
| 2.00 | 1.1045125 | 1.1036826 | 1.1036408 | 1.1036385 | 1.1036383 |
| 2.50 |  | 1.3595575 | 1.3595168 | 1.3595145 | 1.3595144 |
| 3.00 | 1.6701860 | 1.6694308 | 1.6693928 | 1.6693906 | 1.6693905 |
| Table 9.9 |  |  |  |  | Relation between Step Size and E.G.E. for the RK4 Solutions to |

$y^{\prime}=(t-y) / 2$ over $[0,3]$ with $y(0)=1$

| Step <br> size, $h$ | Number of <br> steps, $M$ | Approximation <br> to $y(3), y_{M}$ | F.G.E. <br> Error at $t=3$, <br> $y(3)-y_{M}$ | $O\left(h^{4}\right) \approx C h^{4}$ <br> where <br> $C=-0.000614$ |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 3 | 1.6701860 | -0.0007955 | -0.0006140 |
| $\frac{1}{2}$ | 6 | 1.6694308 | -0.0000403 | -0.0000384 |
| $\frac{1}{4}$ | 12 | 1.6693928 | -0.0000023 | -0.0000024 |
| $\frac{1}{8}$ | 24 | 1.6693906 | -0.0000001 | -0.0000001 |

## Remark:

$$
\begin{aligned}
& y_{k+1}=y_{k}+w_{1} k_{1}+w_{2} k_{2}+w_{3} k_{3}+w_{4} k_{4}, \\
& k_{1}=h f\left(t_{k}, y_{k}\right), \\
& k_{2}=h f\left(t_{k}+a_{1} h, y_{k}+b_{1} k_{1}\right), \\
& k_{3}=h f\left(t_{k}+a_{2} h, y_{k}+b_{2} k_{1}+b_{3} k_{2}\right), \\
& k_{4}=h f\left(t_{k}+a_{3} h, y_{k}+b_{4} k_{1}+b_{5} k_{2}+b_{6} k_{3}\right) .
\end{aligned}
$$

For $k_{2}, k_{3}, k_{4}=0$ we recover Euler's method

## Runge-Kutta Methods of Order $N=2$

$y(t+h)=y(t)+A h f_{0}+B h f_{1}$,

$$
\begin{aligned}
& f_{0}=f(t, y) \\
& f_{1}=f\left(t+P h, y+Q h f_{0}\right)
\end{aligned}
$$

let $\quad f_{1}=f(t, y)+P h f_{t}(t, y)+Q h f_{y}(t, y) f(t, y)+C_{P} h^{2}+\cdots$,
$\longrightarrow \quad y(t+h)=y(t)+(A+B) h f(t, y)+B P h^{2} f_{t}(t, y)$

$$
+B Q h^{2} f_{y}(t, y) f(t, y)+B C_{P} h^{3}+\cdots
$$

Find $A, B, P, Q$ by matching the Runge-Kutta method to $N=2$ Taylor method:

$$
\begin{aligned}
& y(t+h)=y(t)+h y^{\prime}(t)+\frac{1}{2} h^{2} y^{\prime \prime}(t)+C_{T} h^{3}+\cdots, \\
& \left.y^{\prime}(t)=f(t, y) . \quad\right\} \quad y^{\prime \prime}(t)=f_{t}(t, y)+f_{y}(t, y) f(t, y) . \\
& y^{\prime \prime}(t)=f_{t}(t, y)+f_{y}(t, y) y^{\prime}(t) . \\
& y(t+h)=y(t)+h f(t, y)+\frac{1}{2} h^{2} f_{t}(t, y) \\
& \longrightarrow \quad+\frac{1}{2} h^{2} f_{y}(t, y) f(t, y)+C_{T} h^{3}+\cdots .
\end{aligned}
$$

$$
\begin{aligned}
h f(t, y) & =(A+B) h f(t, y) & & \text { implies that } 1=A+B \\
\frac{1}{2} h^{2} f_{t}(t, y) & =B P h^{2} f_{t}(t, y) & & \text { implies that } \frac{1}{2}=B P \\
\frac{1}{2} h^{2} f_{y}(t, y) f(t, y) & =B Q h^{2} f_{y}(t, y) f(t, y) & & \text { implies that } \frac{1}{2}=B Q .
\end{aligned}
$$

Hence, if we require that $A, B, P$, and $Q$ satisfy the relations

$$
A+B=1 \quad B P=\frac{1}{2} \quad B Q=\frac{1}{2},
$$

We need to select one of $A, B, P$ or $Q$

$$
\begin{gathered}
y(t+h)=y(t)+A h f_{0}+B h f_{1} \\
\\
f_{0}=f(t, y) \\
f_{1}=f\left(t+P h, y+Q h f_{0}\right)
\end{gathered}
$$

Case ( $i$ ): Choose $A=\frac{1}{2}$. This choice leads to $B=\frac{1}{2}, P=1$, and $Q=1$. If equation (21) is written with these parameters, the formula is

$$
\begin{equation*}
y(t+h)=y(t)+\frac{h}{2}(f(t, y)+f(t+h, y+h f(t, y))) . \tag{26}
\end{equation*}
$$

When this scheme is used to generate $\left\{\left(t_{k}, y_{k}\right)\right\}$, the result is Heun's method.
Case (ii): Choose $A=0$. This choice leads to $B=1, P=\frac{1}{2}$, and $Q=\frac{1}{2}$. If equation (21) is written with these parameters, the formula is

$$
\begin{equation*}
y(t+h)=y(t)+h f\left(t+\frac{h}{2}, y+\frac{h}{2} f(t, y)\right) \tag{27}
\end{equation*}
$$

When this scheme is used to generate $\left\{\left(t_{k}, y_{k}\right)\right\}$, it is called the modified Euler-Cauchy method.

## Sytem of ODEs

$$
\begin{aligned}
& \frac{d x}{d t}=f(t, x, y) \\
& \frac{d y}{d t}=g(t, x, y)
\end{aligned} \quad \text { with } \quad\left\{\begin{array}{l}
x\left(t_{0}\right)=x_{0} \\
y\left(t_{0}\right)=y_{0}
\end{array}\right.
$$

Seek for solution in $t_{0} \leq t \leq t_{n}$ with

$$
\begin{aligned}
& t_{i}=t_{0}+k h \quad k=0,1, \ldots, M \\
& t_{k+1}-t_{k}=h \quad \text { and } \quad h=\frac{t_{n}-t_{0}}{M}
\end{aligned}
$$

## Euler's approximation

$$
\begin{aligned}
t_{k+1} & =t_{k}+h \\
x_{k+1} & =x_{k}+h f\left(t_{k}, x_{k}, y_{k}\right) \\
y_{k+1} & =y_{k}+h g\left(t_{k}, x_{k}, y_{k}\right) \quad \text { for } k=0,1, \ldots, M-1 .
\end{aligned}
$$

Runge-Kutta method of order $=4($ RK4 $)$

$$
\begin{aligned}
& x_{k+1}=x_{k}+\frac{h}{6}\left(f_{1}+2 f_{2}+2 f_{3}+f_{4}\right), \\
& y_{k+1}=y_{k}+\frac{h}{6}\left(g_{1}+2 g_{2}+2 g_{3}+g_{4}\right)
\end{aligned}
$$

where

$$
\begin{aligned}
f_{1} & =f\left(t_{k}, x_{k}, y_{k}\right), & g_{1} & =g\left(t_{k}, x_{k}, y_{k}\right), \\
f_{2} & =f\left(t_{k}+\frac{h}{2}, x_{k}+\frac{h}{2} f_{1}, y_{k}+\frac{h}{2} g_{1}\right), & g_{2} & =g\left(t_{k}+\frac{h}{2}, x_{k}+\frac{h}{2} f_{1}, y_{k}+\frac{h}{2} g_{1}\right), \\
f_{3} & =f\left(t_{k}+\frac{h}{2}, x_{k}+\frac{h}{2} f_{2}, y_{k}+\frac{h}{2} g_{2}\right), & g_{3} & =g\left(t_{k}+\frac{h}{2}, x_{k}+\frac{h}{2} f_{2}, y_{k}+\frac{h}{2} g_{2}\right), \\
f_{4} & =f\left(t_{k}+h, x_{k}+h f_{3}, y_{k}+h g_{3}\right), & g_{4} & =g\left(t_{k}+h, x_{k}+h f_{3}, y_{k}+h g_{3}\right) .
\end{aligned}
$$

## Higher order ODEs

$$
x^{\prime \prime}(t)=f\left(t, x(t), x^{\prime}(t)\right) \quad \text { with } x\left(t_{0}\right)=x_{0} \text { and } x^{\prime}\left(t_{0}\right)=y_{0}
$$

Reduce the ODE to a system of lower order ODEs

$$
\begin{aligned}
& x^{\prime}(t)=y(t) . \quad \rightarrow \quad x^{\prime \prime}(t)=y^{\prime}(t) \\
& \frac{d x}{d t}=y \quad \text { with } \quad\left\{\begin{array}{l}
x\left(t_{0}\right)=x_{0} \\
y\left(t_{0}\right)=y_{0}
\end{array}\right.
\end{aligned}
$$

Example 9.16. Consider the second-order initial value problem

$$
x^{\prime \prime}(t)+4 x^{\prime}(t)+5 x(t)=0 \quad \text { with } x(0)=3 \text { and } x^{\prime}(0)=-5 .
$$

(a) The differential equation has the form

$$
x^{\prime \prime}(t)=f\left(t, x(t), x^{\prime}(t)\right)=-4 x^{\prime}(t)-5 x(t) .
$$

(b) Using the substitution in (10), we get the reformulated problem:

$$
\begin{aligned}
& \frac{d x}{d t}=y \\
& \frac{d y}{d t}=-5 x-4 y
\end{aligned} \quad \text { with } \quad\left\{\begin{array}{l}
x(0)=3 \\
y(0)=-5
\end{array}\right.
$$

Table 9.14 Runge-Kutta Solution to $x^{\prime \prime}(t)+4 x^{\prime}(t)+5 x(t)=0$ with the Initial Conditions $x(0)=3$ and $x^{\prime}(0)=-5$

| $k$ | $t_{k}$ | $x_{k}$ | $x\left(t_{k}\right)$ |
| ---: | :---: | :---: | :---: |
| 0 | 0.0 | 3.00000000 | 3.00000000 |
| 1 | 0.1 | 2.52564583 | 2.52565822 |
| 2 | 0.2 | 2.10402783 | 2.10404686 |
| 3 | 0.3 | 1.73506269 | 1.73508427 |
| 4 | 0.4 | 1.41653369 | 1.41655509 |
| 5 | 0.5 | 1.14488509 | 1.14490455 |
| 10 | 1.0 | 0.33024302 | 0.33324661 |
| 20 | 2.0 | -0.00620684 | -0.00621162 |
| 30 | 3.0 | -0.00001079 | -0.00701204 |
| 40 | 4.0 | -0.00091163 | -0.00091170 |
| 48 | 4.8 | -0.00004972 | -0.00004969 |
| 49 | 4.9 | -0.00002348 | -0.00002345 |
| 50 | 5.0 | -0.00000493 | -0.00000490 |

## Boundary Value Problem (BVP)

$$
x^{\prime \prime}=f\left(t, x, x^{\prime}\right) \quad \text { for } a \leq t \leq b, \quad x(a)=\alpha \quad \text { and } \quad x(b)=\beta .
$$

Linear BVP
$x^{\prime \prime}=p(t) x^{\prime}(t)+q(t) x(t)+r(t) \quad$ with $x(a)=\alpha$ and $x(b)=\beta$

## Reduction to Two I.V.P.s: Linear Shooting Method

Solution of $\quad x^{\prime \prime}=p(t) x^{\prime}(t)+q(t) x(t)+r(t)$
is given as $\quad x(t)=u(t)+C v(t)$
where $u$ and $v$ are the solutions of the following IVPs:

$$
\begin{aligned}
& u^{\prime \prime}=p(t) u^{\prime}(t)+q(t) u(t)+r(t) \quad \text { with } u(a)=\alpha \text { and } u^{\prime}(a)=0 . \\
& v^{\prime \prime}=p(t) v^{\prime}(t)+q(t) v(t) \quad \text { with } v(a)=0 \text { and } v^{\prime}(a)=1 .
\end{aligned}
$$

proof:

$$
\begin{aligned}
x^{\prime \prime}=u^{\prime \prime}+C v^{\prime \prime} & =p(t) u^{\prime}(t)+q(t) u(t)+r(t)+p(t) C v^{\prime}(t)+q(t) C v(t) \\
& =p(t)\left(u^{\prime}(t)+C v^{\prime}(t)\right)+q(t)(u(t)+C v(t))+r(t) \\
& =p(t) x^{\prime}(t)+q(t) x(t)+r(t) .
\end{aligned}
$$

$$
x(t)=u(t)+C v(t)
$$

Imposing the boundary condition $x(b)=\beta$

$$
\begin{aligned}
& x(b)=u(b)+C v(b) . \quad \rightarrow \quad C=(\beta-u(b)) / v(b) \\
& \text { if } v(b) \neq 0 \\
& x(t)=u(t)+\frac{\beta-u(b)}{v(b)} v(t)
\end{aligned}
$$

## Example 9.17. Solve the boundary value problem

$$
x^{\prime \prime}(t)=\frac{2 t}{1+t^{2}} x^{\prime}(t)-\frac{2}{1+t^{2}} x(t)+1
$$

with $x(0)=1.25$ and $x(4)=-0.95$ over the interval $[0,4]$.

| $t_{j}$ | $u_{j}$ | $w_{j}$ | $x_{j}=u_{j}+w_{j}$ |
| :---: | :---: | :---: | :---: |
| 0.0 | 1.250000 | 0.000000 | 1.250000 |
| 0.2 | 1.220131 | 0.097177 | 1.317308 |
| 0.4 | 1.132073 | 0.194353 | 1.326426 |
| 0.6 | 0.990122 | 0.291530 | 1.281652 |
| 0.8 | 0.800569 | 0.388707 | 1.189276 |
| 1.0 | 0.570844 | 0.485884 | 1.056728 |
| 1.2 | 0.308850 | 0.583061 | 0.891911 |
| 1.4 | 0.022522 | 0.680237 | 0.702759 |
| 1.6 | -0.280424 | 0.777413 | 0.496989 |
| 1.8 | -0.592609 | 0.874591 | 0.281982 |
| 2.0 | -0.907039 | 0.971767 | 0.064728 |
| 2.2 | -1.217121 | 1.068944 | $-0.148177$ |
| 2.4 | -1.516639 | 1.166121 | -0.350518 |
| 2.6 | -1.799740 | 1.263297 | -0.536443 |
| 2.8 | -2.060904 | 1.360474 | -0.700430 |
| 3.0 | -2.294916 | 1.457651 | -0.837265 |
| 3.2 | -2.496842 | 1.554828 | -0.942014 |
| 3.4 | -2.662004 | 1.652004 | -1.010000 |
| 3.6 | -2.785960 | 1.749181 | -1.036779 |
| 3.8 | $-2.864481$ | 1.846358 | -1.018123 |
| 4.0 | -2.893535 | 1.943535 | -0.950000 |

## Finite-Difference Method

Consider the linear equation $\quad x^{\prime \prime}=p(t) x^{\prime}(t)+q(t) x(t)+r(t)$
over $[a, b]$ with $x(a)=\alpha$ and $x(b)=\beta$.

The central-difference formulas

$$
\begin{aligned}
x^{\prime}\left(t_{j}\right) & =\frac{x\left(t_{j+1}\right)-x\left(t_{j-1}\right)}{2 h}+\boldsymbol{O}\left(h^{2}\right) \\
x^{\prime \prime}\left(t_{j}\right) & =\frac{x\left(t_{j+1}\right)-2 x\left(t_{j}\right)+x\left(t_{j-1}\right)}{h^{2}}+\boldsymbol{O}\left(h^{2}\right)
\end{aligned}
$$

$$
\begin{aligned}
& \frac{x_{j+1}-2 x_{j}+x_{j-1}}{h^{2}}=p_{j} \frac{x_{j+1}-x_{j-1}}{2 h}+q_{j} x_{j}+r_{j}, \\
& p_{j}=p\left(t_{j}\right), q_{j}=q\left(t_{j}\right) \text {, and } r_{j}=r\left(t_{j}\right) \\
& \left(\frac{-h}{2} p_{j}-1\right) x_{j-1}+\left(2+h^{2} q_{j}\right) x_{j}+\left(\frac{h}{2} p_{j}-1\right) x_{j+1}=-h^{2} r_{j}, \\
& \text { for } j=1,2, \ldots, N-1, \text { where } x_{0}=\alpha \text { and } x_{N}=\beta .
\end{aligned}
$$



Example 9.18. Solve the boundary value problem

$$
x^{\prime \prime}(t)=\frac{2 t}{1+t^{2}} x^{\prime}(t)-\frac{2}{1+t^{2}} x(t)+1
$$

with $x(0)=1.25$ and $x(4)=-0.95$ over the interval $[0,4]$.

| Table 9.17 Numerical Approximations for $x^{\prime \prime}(t)=\frac{2 t}{1+t^{2}} x^{\prime}(t)-\frac{2}{1+t^{2}} x(t)+1$ |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
|  | $x_{j, 1}$ | $x_{j, 2}$ | $x_{j, 3}$ | $x_{j, 4}$ | $x\left(t_{j}\right)$ |
| $t_{j}$ | $h=0.2$ | $h=0.1$ | $h=0.05$ | $h=0.025$ | exact |
| 0.0 | 1.250000 | 1.250000 | 1.250000 | 1.250000 | 1.250000 |
| 0.2 | 1.314503 | 1.316646 | 1.317174 | 1.317306 | 1.317350 |
| 0.4 | 1.320607 | 1.325045 | 1.326141 | 1.326414 | 1.326505 |
| 0.6 | 1.272755 | 1.279533 | 1.281206 | 1.281623 | 1.281762 |
| 0.8 | 1.177399 | 1.186438 | 1.188670 | 1.189227 | 1.189412 |
| 1.0 | 1.042106 | 1.053226 | 1.055973 | 1.056658 | 1.056886 |
| 1.2 | 0.874878 | 0.887823 | 0.891023 | 0.891821 | 0.892086 |
| 1.4 | 0.683712 | 0.698181 | 0.701758 | 0.702650 | 0.702947 |
| 1.6 | 0.476372 | 0.492027 | 0.495900 | 0.496865 | 0.497187 |
| 1.8 | 0.260264 | 0.276749 | 0.280828 | 0.281846 | 0.282184 |
| 2.0 | 0.042399 | 0.059343 | 0.063537 | 0.064583 | 0.064931 |
| 2.2 | -0.170616 | -0.153592 | -0.149378 | -0.148327 | -0.147977 |
| 2.4 | -0.372557 | -0.355841 | -0.351702 | -0.350669 | -0.350325 |
| 2.6 | -0.557565 | -0.541546 | -0.537580 | -0.536590 | -0.536261 |
| 2.8 | -0.720114 | -0.705188 | -0.701492 | -0.700570 | -0.700262 |
| 3.0 | -0.854988 | -0.841551 | -0.838223 | -0.837393 | -0.837116 |
| 3.2 | -0.957250 | -0.945700 | -0.942839 | -0.942125 | -0.941888 |
| 3.4 | -1.022221 | -1.012958 | -1.010662 | -1.010090 | -1.009899 |
| 3.6 | -1.045457 | -1.038880 | -1.037250 | -1.036844 | -1.036709 |
| 3.8 | -1.022727 | -1.019238 | -1.018373 | -1.018158 | -1.018086 |
| 4.0 | -0.950000 | -0.950000 | -0.950000 | -0.950000 | -0.950000 |

Table 9.18 Errors in Numerical Approximations Using the Finite-Difference Method

|  | $x\left(t_{j}\right)-x_{j, 1}$ <br> $=e_{j, 1}$ | $x\left(t_{j}\right)-x_{j, 2}$ <br> $=e_{j, 2}$ | $x\left(t_{j}\right)-x_{j, 3}$ <br> $=e_{j, 3}$ | $x\left(t_{j}\right)-x_{j, 4}$ <br> $=e_{j, 4}$ |
| :--- | :---: | :---: | :---: | :---: |
| $t_{j}$ | $h_{1}=0.2$ | $h_{2}=0.1$ | $h_{3}=0.05$ | $h_{4}=0.025$ |
| 0.0 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| 0.2 | 0.002847 | 0.000704 | 0.000176 | 0.000044 |
| 0.4 | 0.005898 | 0.001460 | 0.000364 | 0.000091 |
| 0.6 | 0.009007 | 0.002229 | 0.000556 | 0.000139 |
| 0.8 | 0.012013 | 0.002974 | 0.000742 | 0.000185 |
| 1.0 | 0.014780 | 0.003660 | 0.000913 | 0.000228 |
| 1.2 | 0.017208 | 0.004263 | 0.001063 | 0.000265 |
| 1.4 | 0.019235 | 0.004766 | 0.001189 | 0.000297 |
| 1.6 | 0.020815 | 0.005160 | 0.001287 | 0.000322 |
| 1.8 | 0.021920 | 0.005435 | 0.001356 | 0.000338 |
| 2.0 | 0.022533 | 0.005588 | 0.001394 | 0.000348 |
| 2.2 | 0.022639 | 0.005615 | 0.001401 | 0.000350 |
| 2.4 | 0.022232 | 0.005516 | 0.001377 | 0.000344 |
| 2.6 | 0.021304 | 0.005285 | 0.001319 | 0.000329 |
| 2.8 | 0.019852 | 0.004926 | 0.001230 | 0.000308 |
| 3.0 | 0.017872 | 0.004435 | 0.001107 | 0.000277 |
| 3.2 | 0.015362 | 0.003812 | 0.000951 | 0.000237 |
| 3.4 | 0.012322 | 0.003059 | 0.000763 | 0.000191 |
| 3.6 | 0.008749 | 0.002171 | 0.000541 | 0.000135 |
| 3.8 | 0.004641 | 0.001152 | 0.000287 | 0.000072 |
| 4.0 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |


[^0]:    $y_{1}=y\left(t_{0}\right)+\frac{h}{2}\left(f\left(t_{0}, y_{0}\right)+f\left(t_{1}, y_{0}+h f\left(t_{0}, y_{0}\right)\right)\right)$ Heun's method:
    slope at the beginning of slope at the end of step step
    $p_{k+1}=y_{k}+h f\left(t_{k}, y_{k}\right), \quad t_{k+1}=t_{k}+h$,
    
    (a) Derivative predictor:

    $$
    p_{1}=y_{0}+h f\left(t_{0}, y_{0}\right)
    $$

    Local DE $\quad-y^{(2)}\left(c_{k}\right) \frac{h^{3}}{12}$.

    $$
    y_{k+1}=y_{k}+\frac{h}{2}\left(f\left(t_{k}, y_{k}\right)+f\left(t_{k+1}, p_{k+1}\right)\right)
    $$

    
    (b) Integral corrector: $y_{1}-y_{0}=\frac{h}{2}\left(f_{0}+f_{1}\right)$

    Global DE
    $-\sum_{k=1}^{M} y^{(2)}\left(c_{k} \frac{h^{3}}{12} \approx \frac{b-a}{12} y^{(2)}(c) h^{2}=O\left(h^{2}\right)\right.$.

